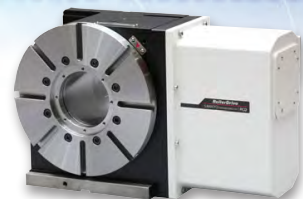


RCD Series

Heavy Duty, Versatile 4-Axis Table

Features

- ▶ Quick indexing capability
- ▶ Excellent accuracy and repeatability
- ▶ Compact size; high speed rotation



Product Code

Rotary table

1	RCD105	-	2	A	3	R	4	B	5	F	6	1	7	H
1	Model		2		3		4		5		6		7	
			Servo motor		Motor mounting side		Connector position		Connector type		Table shape		Posture	
			With brake	Without brake ¹										
	RCD105		A	A1	FANUC	R	Right	B	Rear	F ⁷	Flexible	1	Tapped holes	H ^{9,10} Horizontal position
	RCD170		B ²	B1 ²	MITSUBISHI	L	Left	S ⁵	Side	R	Receptacle	2 ⁶	T slot	V ¹⁰ Upright position
	RCD200		C	C1	— ¹⁵	B ⁴	Rear	T ⁶	Top surface					
	RCD250		D ³	D1 ³	Sanyo Brother type	T ⁴	Top surface							
	RCD300		E	E1	OKUMA									
	RCD400		X	X1	Others (Custom)									

8	EC	-	9	M1	10	W	-	11	X
8	Options		9	Mounting clamps	10	User-supplied items (Motor, MP scale, A/D converter)		11	Standard / Custom
C	Air / Hydraulic clamping		M1	Keys (14 mm width)	W	No user-supplied items (supplied by Sankyo)		Blank	Standard
CH ^{11,13}	Air / Hydraulic clamping External rotary joint		M2	T-slot nuts (14 mm width)	Y	MP scale, A/D converter User supplied		X	Custom
CJ ¹¹	Air / Hydraulic clamping Built-in rotary joint		M3	Mounting clamps (14 mm width)	Z	User-supplied motor			
E ¹¹	With MP scale (MPRZ-536A)		M4	Keys, T-slot nuts (14 mm width)	Blank	Motor, MP scale, A/D converter User supplied			
EC ¹¹	With MP scale (MPRZ-536A) Air / Hydraulic clamping		M5	Keys, Mounting clamps (14 mm width)					
F ¹¹	With MP scale (MPI-536A)		M6	Mounting clamps, T-slot nuts (14 mm width)					
FC ¹¹	With MP scale (MPI-536A) Air / Hydraulic clamping		M7	Keys, Mounting clamps, T-slot nuts (14 mm width)					
H ^{11,13}	External rotary joint		M8 ¹⁴	Mounting clamps (14 mm width) [For option J horizontal placement]					
J ¹¹	Built-in rotary joint		M9 ¹⁴	Keys, Mounting clamps (14 mm width) [For option J horizontal placement]					
G ^{11,12}	With MP scale (MPRZ-536A) Air / Hydraulic clamping Built-in rotary joint		MA ¹⁴	Mounting clamps, T-slot nuts (14 mm width) [For option J horizontal placement]					
K ^{11,12}	With MP scale (MPI-536A) Air / Hydraulic clamping Built-in rotary joint		MB ¹⁴	Keys, Mounting clamps, T-slot nuts (14 mm width) [For option J horizontal placement]					
Blank	No options		MC	Keys (18 mm width)					
			MD	T-slot nuts (18 mm width)					
			ME	Mounting clamps (18 mm width)					
			MF	Keys, T-slot nuts (18 mm width)					
			MG	Keys, Mounting clamps (18 mm width)					
			MH	Mounting clamps, T-slot nuts (18 mm width)					
			MI	Keys, Mounting clamps, T-slot nuts (18 mm width)					
			MJ ¹⁴	Mounting clamps (18 mm width) [For option J horizontal placement]					
			MK ¹⁴	Keys, Mounting clamps (18 mm width) [For option J horizontal placement]					
			ML ¹⁴	Mounting clamps, T-slot nuts (18 mm width) [For option J horizontal placement]					
			MM ¹⁴	Keys, Mounting clamps, T-slot nuts (18 mm width) [For option J horizontal placement]					
			MN	Keys (22 mm width)					
			MO	T-slot nuts (22 mm width)					
			MP	Mounting clamps (22 mm width)					
			MQ	Keys, T-slot nuts (22 mm width)					
			MR	Keys, Mounting clamps (22 mm width)					
			MS	Mounting clamps, T-slot nuts (22 mm width)					
			MT	Keys, Mounting clamps, T-slot nuts (22 mm width)					
			Blank	No mounting clamps					

*1 If motor brake control is not possible, select a servo motor without brake.

*2 The standard Sankyo-supplied motor for motor code B1 (B) is HF □□□ (B) S-A48.

*3 For RCD105, select "Without brake". For RCD170 to RCD300, select "With brake". RCD400 is not available with the Sanyo Brother type motor.

*4 RCD105 is not available in the motor top surface type or motor rear surface type.

*5 Models of the motor top surface type are not available with the side connector position.

*6 Only models of the motor top surface type are available with the top surface connector position.

*7 If "Flexible" is selected, the flexible cable code must also be selected.

*8 For RCD105, the T slot table cannot be selected.

*9 Models of the motor rear surface type and motor top surface type are not available with the horizontal placement posture.

*10 Models supporting both postures are available (custom).

*11 There is no hollow bore in the table when the MP scale (high-accuracy model) or rotary joint is installed.

*12 Options G and K are only available for RCD250 to RCD400 models of the motor top surface type. MP scales (high-accuracy type) and rotary joints can't be used together in models of other types.

*13 Options CH and H are not available for models of the motor rear surface type and motor top surface type.

*14 Options M8 to MB and MJ to MM are only available for models RCD105 to 200 of the motor right / left mounting type.

*15 Contact Sankyo for information about the external controller type.

Motor mounting side	Connector position	Connector type / shape	Table shape
R	B	F	1
L	S	R	
B	T		
T			2 ⁸

Product Code

Flexible cable

1		CD-105		-	2		A		3		A		4		S		5		3		6		R		-	7		X	
1					2				3				4				5				6					7			
Model					Servo motors for rotary tables				Type of flexible connector at rotary table side				Type of connector at customer side				Length				Flexible material					Standard / Custom			
					With brake	Without brake ¹⁾		Manufacturer																					
CD-105	For RCD105				A	A1		FANUC		S	Straight		S	Straight		3	3m		R	Resin			Blank	Standard					
CD-170	For RCD170				B	B1		MITSUBISHI		A	Angled		A	Angled		5	5m		M	Metal			X	Custom					
CD-200	For RCD200				C	C1		— ⁶⁾																					
CD-250	For RCD250 and RCD300				D ²⁾	D1 ²⁾		Sanyo Brother type																					
CD-400	For RCD400				E	E1		OKUMA																					
					X	X1		Others (Custom)																					

¹⁾ If motor brake control is not possible, select a servo motor without brake.

²⁾ For RCD105, select "Without brake". For RCD170 to RCD300, select "With brake". RCD400 is not available with the Sanyo Brother type motor.

⁶⁾ Contact Sanyo for information about the external controller type.

Support table

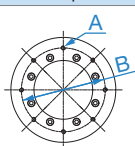
1	ST105A	2	1	3	CH	4	M1	5	X
1	Model	2		3		4		5	
		Table shape		Options		Mounting clamps		Standard / Custom	
ST105A	For RCD105	1	Tapped holes	C	Air / Hydraulic clamping	M1	Keys (14 mm width)	Blank	Standard
ST170A	RCD170, For 200	2 ³⁾	T slot	CH ⁴⁾	Air / Hydraulic clamping External rotary joint	M2	T-slot nuts (14 mm width)	X	Custom
ST250A	For RCD250 and RCD300			CJ ⁴⁾	Air / Hydraulic clamping Built-in rotary joint	M4	Keys T-slot nuts (14 mm width)		
ST400A	For RCD400			H ⁴⁾	External rotary joint	MC	Keys (18 mm width)		
				J ^{4), 5)}	Built-in rotary joint	MD	T-slot nuts (18 mm width)		
				Blank	No options	MF	Keys T-slot nuts (18 mm width)		
						MN	Keys (22 mm width)		
						MO	T-slot nuts (22 mm width)		
						MQ	Keys T-slot nuts (22 mm width)		
						Blank	No mounting clamps		

³⁾ For ST105A, the T slot table cannot be selected.

⁴⁾ There is no hollow bore in the table when a rotary joint is mounted.

⁵⁾ Option J is not available (is the same as option H) for ST400A.

Table shape



	A	B
ST105A	(4)M8 × 1.25, 16DP	75
ST170A	(8)M8 × 1.25, 14DP	140
ST250A	(8)M10 × 1.5, 18DP	210
ST400A	(8)M12 × 1.75, 24DP	355

2³⁾ P21 ~ 22 : Table with ST dimensions

Tail stock

1	TSS105	2	M	3	R	4	M1	5	X
1	Model	2		3		4		5	
		Type		Handle side		Mounting clamps		Standard / Custom	
TSS105	For RCD105	M	Manual	R	Right	M1	Keys (14 mm width)	Blank	Standard
TSS135	For RCD170 and RCD200			L	Left	M2	T-slot nuts (14 mm width)	X	Custom
TSS185	For RCD250 and RCD300					M4	Keys T-slot nuts (14 mm width)		
TSS230	For RCD400					MC	Keys (18 mm width)		
						MD	T-slot nuts (18 mm width)		
						MF	Keys T-slot nuts (18 mm width)		
						MN	Keys (22 mm width)		
						MO	T-slot nuts (22 mm width)		
						MQ	Keys T-slot nuts (22 mm width)		
						Blank	No mounting clamps		

Specifications (RCD models of motor side surface mounting type)

Specifications			RCD105	RCD170	RCD200	RCD250	RCD300	RCD400
Table diameter		mm	Φ 105	Φ 170	Φ 200	Φ 250	Φ 300	Φ 400
Table pilot bore diameter		mm	Φ 60 ^{+0.03} ₀	Φ 60 ^{+0.03} ₀	Φ 60 ^{+0.03} ₀	Φ 110 ^{+0.035} ₀	Φ 110 ^{+0.035} ₀	Φ 150 ^{+0.04} ₀
Center height		mm	105	135	135	185	185	230
Table T slot width		mm	—	12 ^{+0.018} ₀	12 ^{+0.018} ₀	12 ^{+0.018} ₀	12 ^{+0.018} ₀	14 ^{+0.018} ₀
Keyway width		mm	14 ⁰ _{-0.011}	14 ⁰ _{-0.011}	14 ⁰ _{-0.011}	18 ⁰ _{-0.011}	18 ⁰ _{-0.011}	18 ⁰ _{-0.011}
Clamp type (air 0.5 MPa, hydraulic 3.5 MPa)			Air / Hydraulic	Air / Hydraulic	Air / Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamp torque ^{*1}		N·m	210	310	310	1100	1100	1850
Motor shaft equivalent inertia ^{*2,*3}		× 10 ⁻⁴ kg·m ²	0.56	2.96	3.15	5.70	5.70	25.76
Motor model (FANUC)			α iS2/5000-B (A06B-2212-B400)	α iS4/5000-B (A06B-2215-B400)	α iS8/4000-B (A06B-2235-B400)	α iS8/4000-B (A06B-2235-B400)	α iS8/4000-B (A06B-2235-B400)	α iS22/4000-B (A06B-2265-B400)
Minimum setting unit		deg	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001
Maximum table speed		min ⁻¹	100	70	70	60	60	60
Gear ratio ^{*2}			1/50	1/50	1/50	1/60	1/60	1/60
Indexing accuracy		arc.sec	± 15	± 15	± 15	± 10	± 10	± 10
Repeatability		arc.sec	8	8	8	4	4	4
Net weight		kg	30	51	59	110	115	263
Allowable payload	Upright position ^{*4} 	kg	50 (100)	70 (140)	70 (140)	255 (510)	255 (510)	295 (590)
	Horizontal position 	kg	100	140	140	510	510	590
Allowable load	F 	N	18200	21000	21000	52000	52000	58500
	F × L with clamping 	N · m	210	310	310	1100	1100	1850
	Continuous holding torque ^{*2,*5}	N · m	122	236	416	512	512	1400
	Maximum output torque ^{*2,*5,*6}	N · m	221	362	544	987	987	2400
	F × L 	N · m	900	1300	1300	5500	5500	7800
Allowable workpiece inertia		kg·m ²	0.5	1.1	1.1	8.3	8.3	15
External rotary joint (number of ports) ^{*7}			6+1	6+1	6+1	10+1	10+1	12+1
Internal rotary joint (number of ports) ^{*7}			4	6	6	8	8	10
MP scale (high-accuracy model) ^{*7}			MPRZ-536A (MHI)					
			MPI-536A (MHI)					

*1 Values for RCD105, RCD170, and RCD200 are clamping torques when using an air hydro booster with a air pressure of 0.5 MPa as the supply source.

*2 Values for motor shaft equivalent inertia, gear ratio, and continuous / maximum holding torque are given for Fanuc motors. Please contact Sankyo if a different motor is to be used.

*3 Motor shaft equivalent inertia does not include the inertia of the motor shaft.

*4 The allowable payload value for upright mounting shown in brackets applies when a tail stock or support table is used.

*5 The continuous / maximum holding torque is the allowable load torque when a clamp is not used.

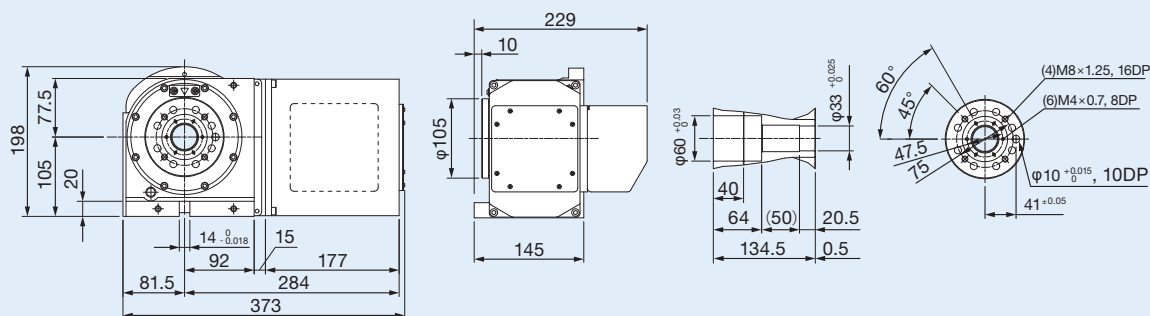
*6 Maximum holding torque should not exceed 10 seconds with 20% duty.

*7 Simultaneous use of the MP scale (high-accuracy model) and the rotary joint is not supported.



Dimensions (RCD models of motor side surface mounting type)

► RCD105



► RCD170

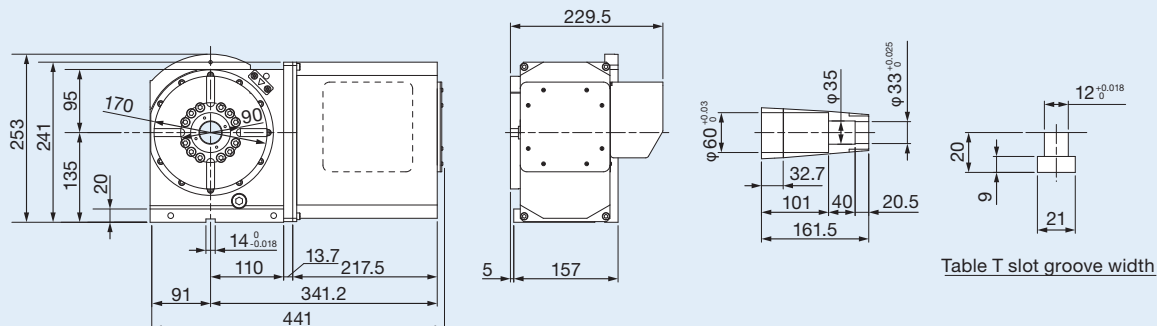


Table T slot groove width

► RCD200

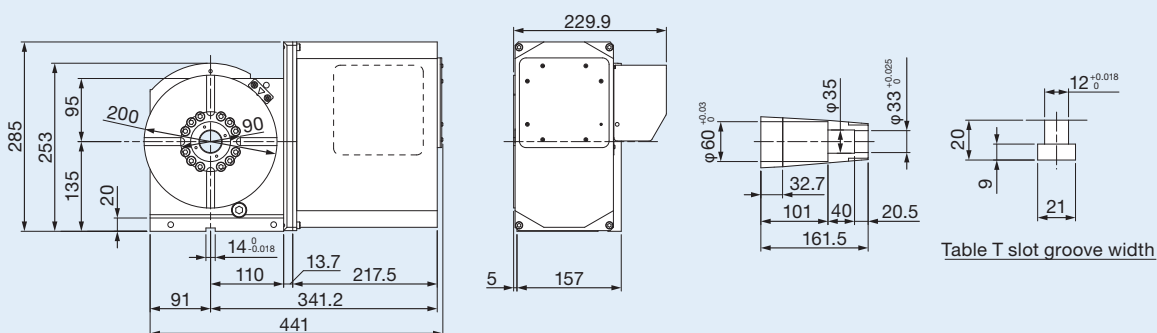


Table T slot groove width

► RCD250

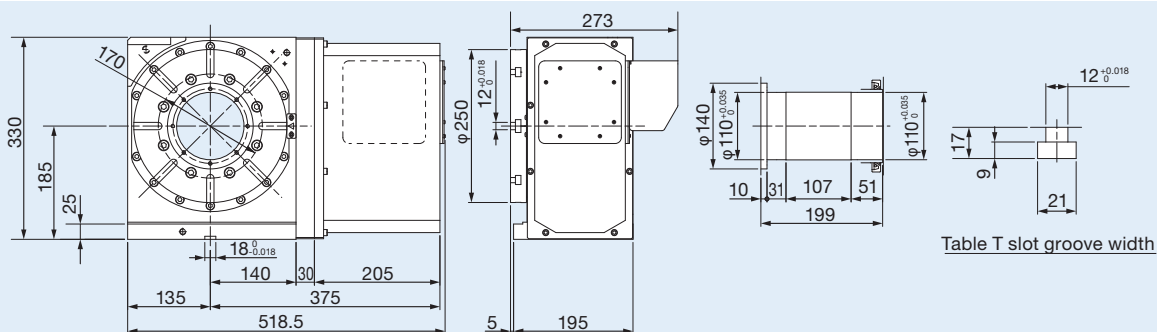


Table T slot groove width

► RCD300

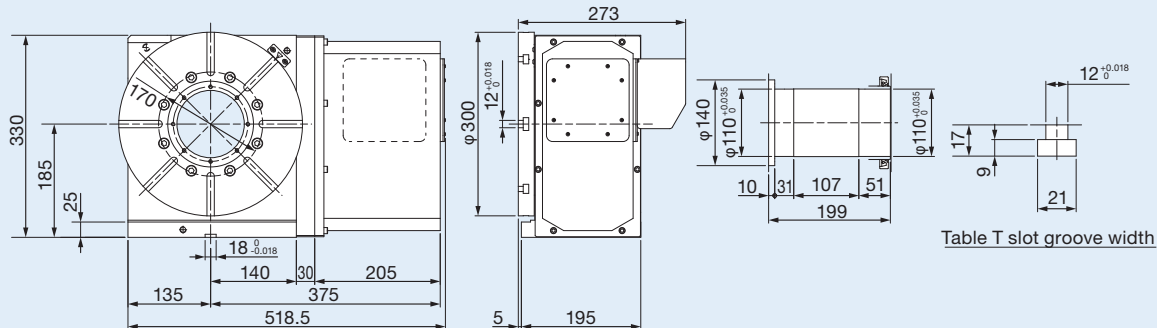
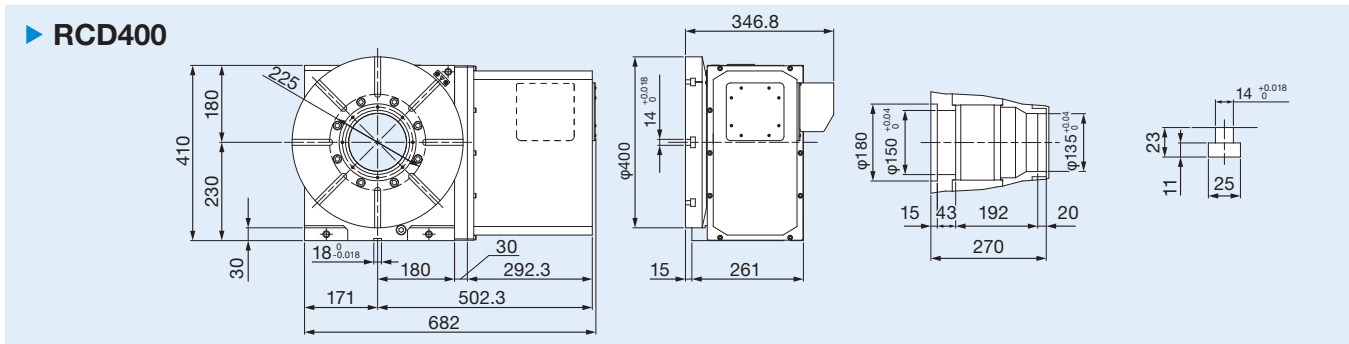


Table T slot groove width

Specifications (RCD models of motor side surface mounting type)

The drawings apply to the following specifications: Fanuc motor, R side mounting, rear connector.





Specifications (RCD models of motor rear surface mounting type)

Specifications			RCD170	RCD200	RCD250	RCD300	RCD400
Table diameter		mm	Φ 170	Φ 200	Φ 250	Φ 300	Φ 400
Table pilot bore diameter		mm	Φ 60 ^{+0.03} ₀	Φ 60 ^{+0.03} ₀	Φ 110 ^{+0.035} ₀	Φ 110 ^{+0.035} ₀	Φ 150 ^{+0.04} ₀
Center height		mm	185	185	185	185	230
Table T slot width		mm	12 ^{+0.018} ₀	12 ^{+0.018} ₀	12 ^{+0.018} ₀	12 ^{+0.018} ₀	14 ^{+0.018} ₀
Keyway width		mm	14 ⁰ _{-0.011}	14 ⁰ _{-0.011}	18 ⁰ _{-0.011}	18 ⁰ _{-0.011}	18 ⁰ _{-0.011}
Clamp type (air 0.5 MPa, hydraulic 3.5 MPa)			Air / Hydraulic	Air / Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamp torque ^{*1}		N·m	310	310	1100	1100	1850
Motor shaft equivalent inertia ^{*2, *3}		× 10 ⁻⁴ kg·m ²	6.14	6.33	10.90	11.10	47.76
Motor model (FANUC)			α iS8/4000-B (A06B-2235-B400)	α iS8/4000-B (A06B-2235-B400)	α iS8/4000-B (A06B-2235-B400)	α iS8/4000-B (A06B-2235-B400)	α iS22/4000-B (A06B-2265-B400)
Minimum setting unit		deg	0.0001	0.0001	0.0001	0.0001	0.0001
Maximum table speed		min ⁻¹	70	70	60	60	60
Gear ratio			1/50	1/50	1/60	1/60	1/60
Indexing accuracy		arc.sec	± 15	± 15	± 10	± 10	± 10
Repeatability		arc.sec	8	8	4	4	4
Net weight		kg	78	80	133	138	305
Allowable payload	Upright position ^{*4} 	kg	70 (140)	70 (140)	255 (510)	255 (510)	295 (590)
Allowable load	F 	N	21000	21000	52000	52000	58500
	F × L with clamping 	N · m	310	310	1100	1100	1850
	Continuous holding torque ^{*2, *5}	N · m	416	416	512	512	1400
	Maximum output torque ^{*2, *5, *6}	N · m	544	544	987	987	2400
	F × L 	N · m	1300	1300	5500	5500	7800
Allowable workpiece inertia		kg·m ²	1.1	1.1	8.2	8.2	15
Internal rotary joint (number of ports) ^{*7}			6	6	8	8	10
MP scale (high-accuracy model) ^{*7}			MPRZ-536A (MHI)				
			MPI-536A (MHI)				

*1 Values for RCD170, RCD200 are clamping torques when using an air hydro booster with a air pressure of 0.5 MPa as the supply source.

*2 The values shown for motor shaft equivalent inertia and continuous/maximum holding torque apply when using a Fanuc motor. Contact Sankyo if using a different motor.

*3 Motor shaft equivalent inertia does not include the inertia of the motor shaft.

*4 The allowable payload value for upright mounting shown in brackets applies when a tail stock or support table is used.

*5 The continuous / maximum holding torque is the allowable load torque when a clamp is not used.

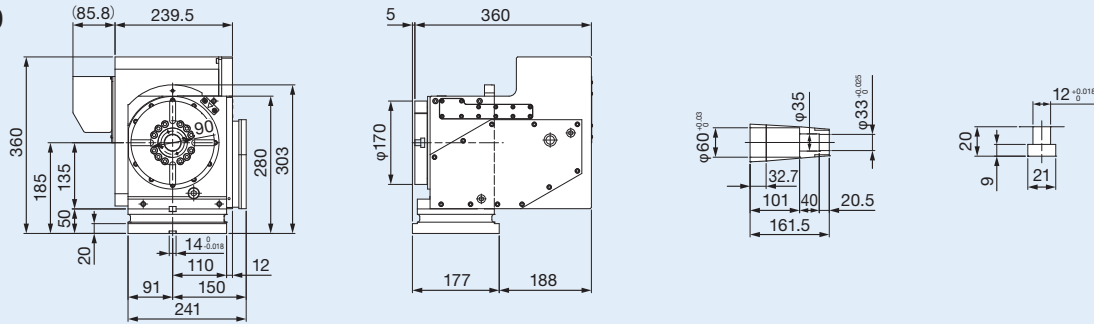
*6 Maximum holding torque should not exceed 10 seconds with 20% duty.

*7 Simultaneous use of the MP scale (high-accuracy model) and the rotary joint is not supported.

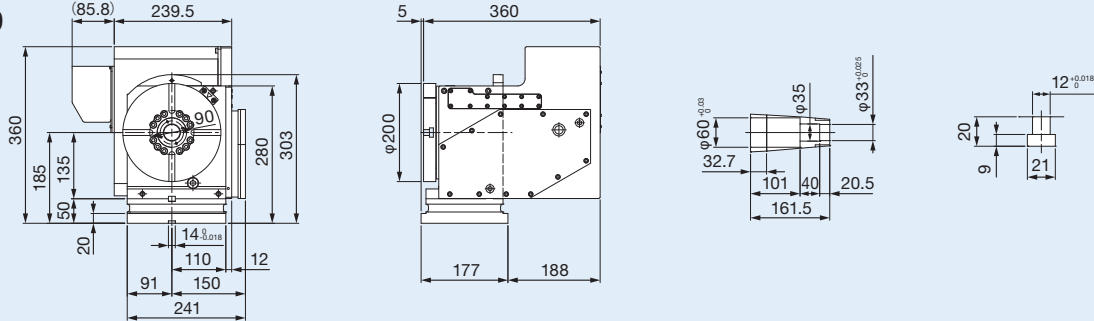
Dimensions (RCD models of motor rear surface mounting type)

The drawings apply to the following specifications: Fanuc motor, side connector.

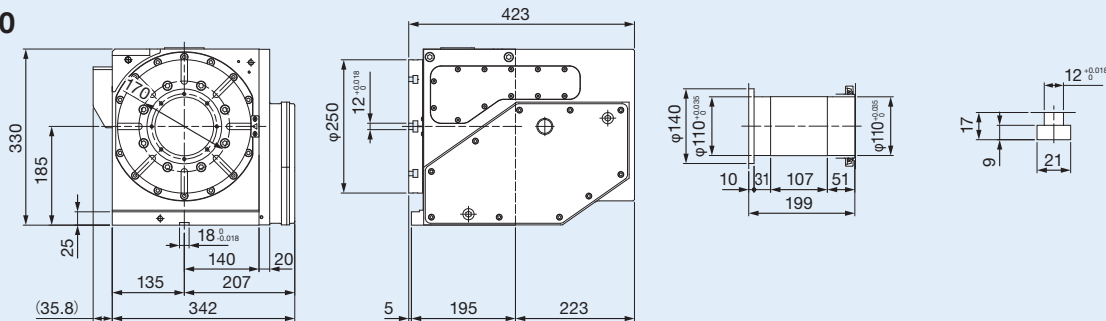
► RCD170



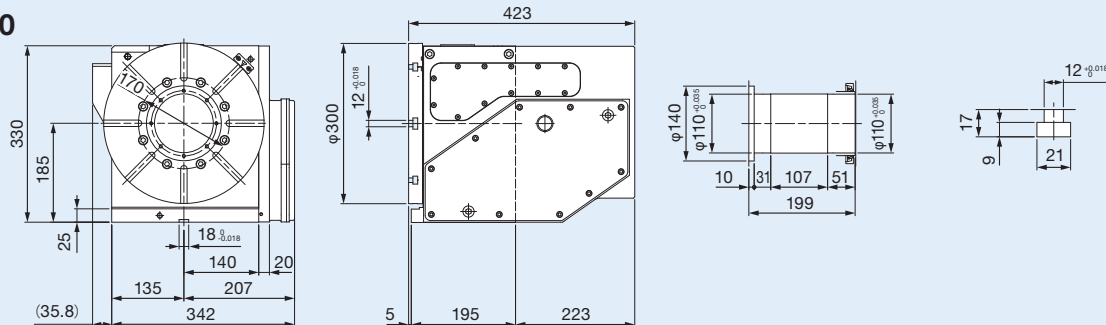
► RCD200



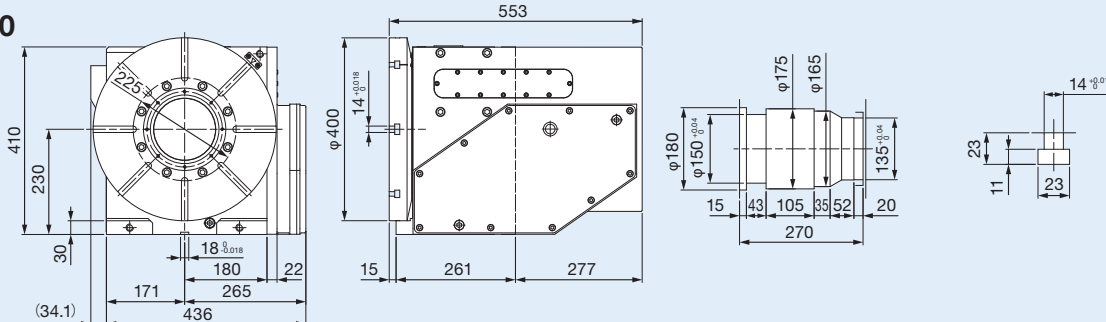
► RCD250



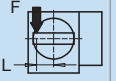
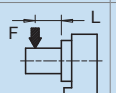
► RCD300



► RCD400



Specifications (RCD models of motor top surface mounting type)

Specifications			RCD170	RCD200	RCD250	RCD300	RCD400
Table diameter	mm		Φ 170	Φ 200	Φ 250	Φ 300	Φ 400
Table pilot bore diameter	mm		Φ 60 $^{+0.03}_0$	Φ 60 $^{+0.03}_0$	Φ 110 $^{+0.035}_0$	Φ 110 $^{+0.035}_0$	Φ 150 $^{+0.04}_0$
Center height	mm		135	135	185	185	230
Table T slot width	mm		12 $^{+0.018}_0$	12 $^{+0.018}_0$	12 $^{+0.018}_0$	12 $^{+0.018}_0$	14 $^{+0.018}_0$
Keyway width	mm		14 $^0_{-0.011}$	14 $^0_{-0.011}$	18 $^0_{-0.011}$	18 $^0_{-0.011}$	18 $^0_{-0.011}$
Clamp type (air 0.5 MPa, hydraulic 3.5 MPa)			Air / Hydraulic	Air / Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamp torque ^{*1}	N·m		310	310	1100	1100	1850
Motor shaft equivalent inertia ^{*2, *3}	$\times 10^{-4}$ kg·m ²		2.96	3.15	5.70	5.70	25.76
Motor model (FANUC)			α iS4/4000-B (A06B-2215-B400)	α iS8/4000-B (A06B-2235-B400)	α iS8/4000-B (A06B-2235-B400)	α iS8/4000-B (A06B-2235-B400)	α iS22/4000-B (A06B-2265-B400)
Minimum setting unit	deg		0.0001	0.0001	0.0001	0.0001	0.0001
Maximum table speed	min ⁻¹		70	70	60	60	60
Gear ratio			1/50	1/50	1/60	1/60	1/60
Indexing accuracy	arc.sec		± 15	± 15	± 10	± 10	± 10
Repeatability	arc.sec		8	8	4	4	4
Net weight	kg		61	69	120	125	291
Allowable payload	Allowable load ^{*4} 	kg	70 (140)	70 (140)	255 (510)	255 (510)	295 (590)
Upright position	F 	N	21000	21000	52000	52000	58500
	F × L with clamping 	N · m	310	310	1100	1100	1850
	Continuous holding torque ^{*2, *5}	N · m	236	416	512	512	1400
	Maximum output torque ^{*2, *5, *6}	N · m	362	544	987	987	2400
	F × L 	N · m	1300	1300	5500	5500	7800
Allowable workpiece inertia	kg·m ²		1.1	1.1	8.2	8.2	15
External rotary joint (number of ports) ^{*7}			6+1	6+1	10+1	10+1	12+1
Internal rotary joint (number of ports) ^{*7}			6	6	8	8	10
MP scale (high-accuracy model) ^{*7}			MPRZ-536A (MHI)				
			MPI-536A (MHI)				

*1 Values for RCD170, RCD200 are clamping torques when using an air hydro booster with a air pressure of 0.5 MPa as the supply source.

*2 The values shown for motor shaft equivalent inertia and continuous/maximum holding torque apply when using a Fanuc motor. Contact Sankyo if using a different motor.

*3 Motor shaft equivalent inertia does not include the inertia of the motor shaft.

*4 The allowable payload value for upright mounting shown in brackets applies when a tail stock or support table is used.

*5 The continuous / maximum holding torque is the allowable load torque when a clamp is not used.

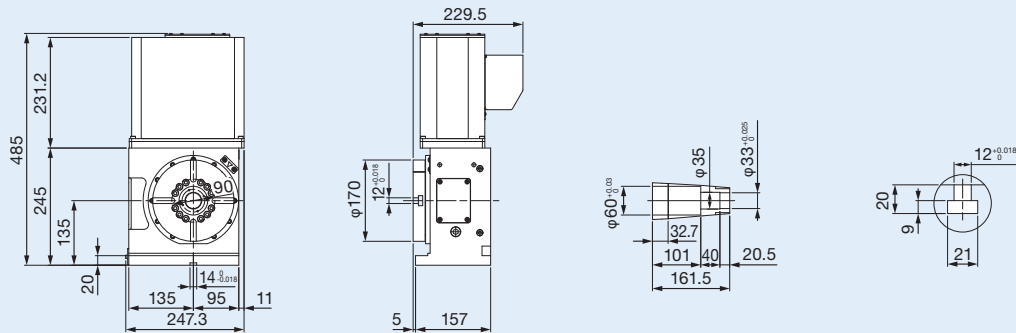
*6 Maximum holding torque should not exceed 10 seconds with 20% duty.

*7 Models RCD105, RCD170, and RCD200 do not enable the use of MP scales (high-accuracy type) together with rotary joints.

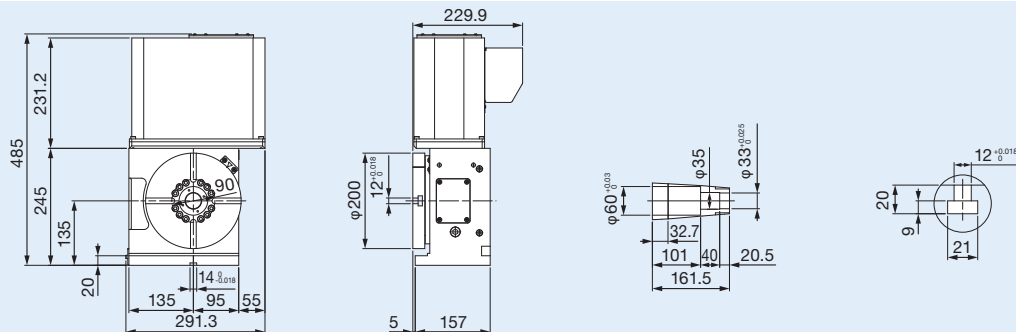
Dimensions (RCD models of motor top surface mounting type)

The drawings apply to the following specifications: Fanuc motor, rear connector.

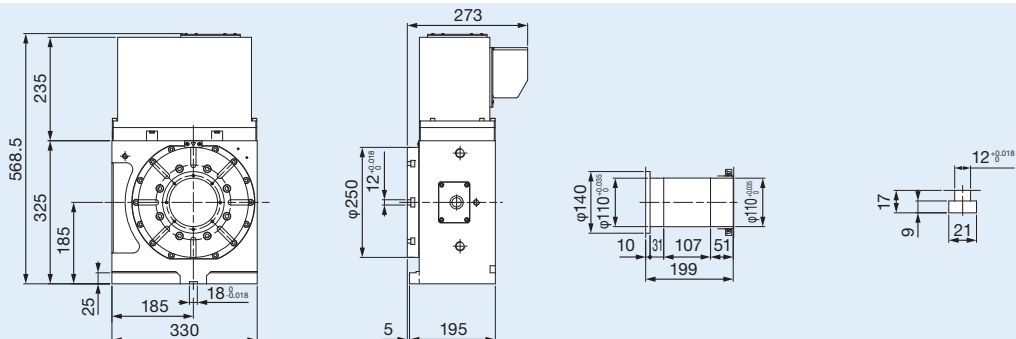
► RCD170



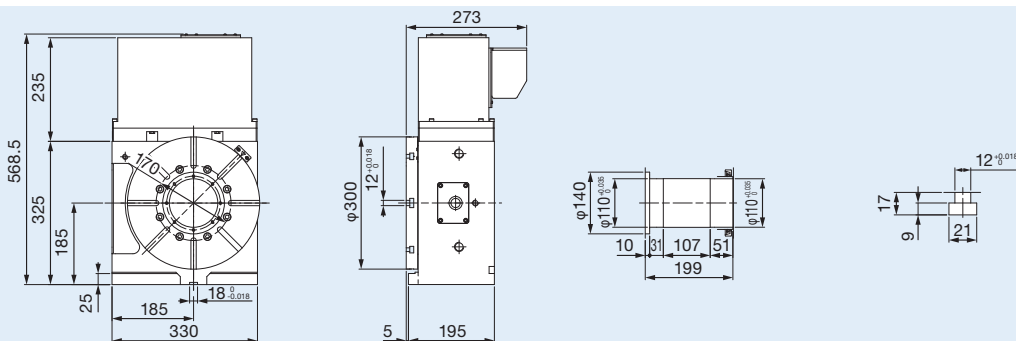
► RCD200



► RCD250



► RCD300



► RCD400

